

Chen Sun

ASSISTANT PROFESSOR · UNIVERSITY OF HONG KONG

Haking Wong Building, The University of Hong Kong, Pokfulam Road, Hong Kong

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Education

University of Waterloo

Waterloo, ON, Canada

PH.D. MECHANICAL & MECHATRONICS ENGINEERING

2018.09 - 2022.12

- Dissertation: “Operational Design Domain Monitoring and Augmentation for Autonomous Driving”
- Advisor: Prof. Amir Khajepour

University of Toronto

Toronto, ON, Canada

M.A.SC. ELECTRICAL & COMPUTER ENGINEERING

2014.09 - 2017.03

- Thesis: “Fast FDTD Algorithm based on Model Order Reduction”
- Advisor: Prof. Piero Triverio

University of Electronic Science and Technology of China

Chengdu, Sichuan, China

B.ENG. SYSTEM CONTROL

2010.09 - 2014.07

- Honor’s Thesis: “Top tension control of a flexible marine riser by using integral-barrier Lyapunov function”
- Undergrad research advisor: Prof. Shuzhi Sam Ge & Prof. Wei He

Work Experience

- 2024.09 - Current **Assistant Professor**, University of Hong Kong
- 2022.12 - 2024.09 **Postdoctoral Fellow**, Mechatronic Vehicle Systems Lab, University of Waterloo
- 2022.01 - 2023.06 **Consultant - Autonomous Driving Stack**, Waytous Inc., (Beijing, China)
- 2017.05 - 2018.08 **R&D Engineer - System Control**, Robot Control Branch-Xylem Inc. (Mississauga, Canada)
- 2017.01 - 2017.04 **Intern - Software Developer**, Bell Canada (Toronto, Canada)

Publications

SELECTED JOURNAL PAPERS (CORRESPONDING AUTHOR *)

- Sun, C.**, Cui, Y., Ning, M., Lu, Y., Cao, D., & Khajepour, A. (2024). Extending Operational Design Domain for Perception Systems Through Robust Learning. *IEEE Transactions on Vehicular Technology*.
- Sun, C.**, Ning, M., Deng, Z., & Khajepour, A. (2024). REAL-SAP: Real-time Evidence Aware Liable Safety Assessment for Perception in Autonomous Driving. *IEEE Transactions on Vehicular Technology*.
- Wang, X., Huang, J., Tian, Y., **Sun, C.**, Yang, L., Lou, S., Lv, C., Sun, C. & Wang, F.Y., 2024. Parallel Driving with Big Models and Foundation Intelligence in Cyber-Physical-Social Spaces. *Research*. 7, p.0349.
- Lu, Y., Huang, Y., **Sun, C.**, Zhong, J., & Khajepour, A. (2024). An interconnected suspension with adjustable roll and pitch stiffness (IS-ARPS) to enhance anti-roll and anti-dive/squat characteristics. *Proceedings of the Institution of Mechanical Engineers, Part D: Journal of Automobile Engineering*.
- Wang, H., Shao, W., **Sun, C. ***, Yang, K., Cao, D., & Li, J. (2024). A Survey on an Emerging Safety Challenge for Autonomous Vehicles: Safety of the Intended Functionality. *Engineering*.
- Sun, C.**, Cui, Y., Đào, N. D., Mehrizi, R. V., Pirani, M., & Khajepour, A. (2023). Medium-Fidelity Evaluation and Modeling for Perception Systems of Intelligent and Connected Vehicles. *IEEE Transactions on Intelligent Vehicles*.
- Sun, C.**, Zhang, R., Cui, Y., Deng, Z., Cao, D., & Khajepour, A. (2023). Towards Ensuring Safety for Autonomous Driving Perception: Standardization Progress, Research Advances, and Perspectives. *IEEE Transactions on Intelligent Transportation Systems*
- Cui, Y., Huang, S., Zhong, J., Liu, Z., Wang, Y., **Sun, C. ***, ... & Khajepour, A. (2023). DriveLLM: Charting the path toward full autonomous driving with large language models. *IEEE Transactions on Intelligent Vehicles*.

- Wu, X., Ma, Y., Fu, Q., **Sun, C.**, Zhu, B., & He, W. (2022). Anti-Disturbance Boundary Control for a Wave Equation With Input Disturbance. *IEEE Transactions on Systems, Man, and Cybernetics: Systems*, 53(4), 2236-2245.
- Sun, C.**, Li, S., Cao, D., Wang, F. Y., & Khajepour, A. (2022). Tabular Learning-Based Traffic Event Prediction for Intelligent Social Transportation System. *IEEE Transactions on Computational Social Systems*.
- Ma, Y., **Sun, C.**, Chen, J., Cao, D., & Xiong, L. (2022). Verification and validation methods for decision-making and planning of automated vehicles: A review. *IEEE Transactions on Intelligent Vehicles*.
- Su, L., **Sun, C.** *, Cao, D., & Khajepour, A. (2022). Efficient driver anomaly detection via conditional temporal proposal and classification network. *IEEE Transactions on Computational Social Systems*, 10(2), 736-745.
- Sun, C.** , Deng, Z., Chu, W., Li, S., & Cao, D. (2021). Acclimatizing the operational design domain for autonomous driving systems. *IEEE Intelligent Transportation Systems Magazine*, 14(2), 10-24.
- Sun, C.** , Wang, C., Deng, Z., & Cao, D. (2020). Dimensionless model-based system tracking via augmented Kalman filter for multiscale unmanned ground vehicles. *IEEE/ASME Transactions on Mechatronics*, 26(2), 600-610.
- Sun, C.** , Vianney, J. M. U., Li, Y., Chen, L., Li, L., Wang, F. Y., ... & Cao, D. (2020). Proximity based automatic data annotation for autonomous driving. *IEEE/CAA Journal of Automatica Sinica*, 7(2), 395-404.

CONFERENCE PAPERS

- Sun, C.** , Cui, Y., Lu, Y., Cao, Y., Cao, D., & Khajepour, A. (2023, November). Robust Learning for Autonomous Driving Perception Tasks in Cyber-Physical-Social Systems. In *2023 IEEE 3rd International Conference on Digital Twins and Parallel Intelligence (DTPI)* (pp. 1-7). IEEE.
- Sun, C.** , Cui, Y., Đào, N. D., & Khajepour, A. (2023, August). Delay Mitigation for V2I-based Cooperative Autonomous Driving Applications. In the *28th IAVSD International Symposium on Dynamics of Vehicles on Roads and Tracks (IAVSD)*
- Sun, C.** , Tan, R., Deng, J., Zhou, R., Chen, L., Wang, F. Y., & Cao, D. (2021, July). Accident prediction in mesoscopic view: A cps-based social transportation approach. In *2021 IEEE 1st International Conference on Digital Twins and Parallel Intelligence (DTPI)* (pp. 306-311).
- Peng, M., Gong, Z., **Sun, C.** , Chen, L., & Cao, D. (2020, May). Imitative reinforcement learning fusing vision and pure pursuit for self-driving. In *2020 IEEE International Conference on Robotics and Automation (ICRA)* (pp. 3298-3304). IEEE.
- Sun, C.** , Su, L., Gu, S., Vianney, J. M. U., Qin, K., & Cao, D. (2019, October). Cross validation for CNN based affordance learning and control for autonomous driving. In *2019 IEEE Intelligent Transportation Systems Conference (ITSC)* (pp. 1519-1524). IEEE.

Funding, Awards & Fellowships

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|-------------|--|
| 2023 | Canada Mitacs Accelerate internships , Mitacs, Canada |
| 2022 | Chinese Government Award for Outstanding Self-financed Students Abroad ,
China Scholarship Council |
| 2019 - 2022 | University of Waterloo Graduate Scholarship , University of Waterloo |
| 2021 | Outstanding paper award , 2021 IEEE 1st International Conference on Digital
Twins and Parallel Intelligence (DTPI) |
| 2014 - 2016 | University of Toronto Rogers scholarship , University of Toronto |
| 2011 - 2014 | People's First Class Scholarship , University of Electronic Science and
Technology of China |

Teaching Experience

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|-------------|---|-------------------------------|
| Summer 2023 | Introduction to Autonomous Driving Systems (ME780) , Guest Lecturer | <i>University of Waterloo</i> |
| Fall 2020 | Introduction to Control Systems (ME360) , Teaching Assistant | <i>University of Waterloo</i> |
| 2019 - 2021 | Introduction to Microprocessors and Digital Logic (ME262) , Teaching Assistant | <i>University of Waterloo</i> |
| Summer 2019 | Advanced Calculus (MTE203) , Teaching Assistant | <i>University of Waterloo</i> |
| 2015 - 2016 | Digital Systems (ECE241) , Teaching Assistant | <i>University of Toronto</i> |
| Fall 2015 | Introduction to Computer Programming (CSC108) , Teaching Assistant | <i>University of Toronto</i> |

Mentorship Activities

2024 - Current **Bruce Wang**, Undergraduate Research Assistant, University of Waterloo

2020 - 2021 **Lang Su**, Undergraduate Research Assistant, University of Waterloo

Patent

Wang, F., Chen, L., Cao, D., Tian, B., & **Sun, C.** (2024). Intelligent Driving System, U.S. Patent Application No. 18/035,639.

Review Activities

IEEE Transactions on Intelligent Vehicles (TIV)

IEEE Transactions on Cybernetics (TCYB)

IEEE Transactions on Artificial Intelligence (TAI)

EE/ASME Transactions on Mechatronics (TMECH)

IEEE Transactions on Fuzzy Systems (TFS)

Automotive Innovation (AUIN)

IEEE Intelligent Transportation Systems Conference (ITSC)

IEEE International Conference on Intelligent Robots and Systems (IROS)

Languages and Tools

Proficient in **Python, MATLAB/Simulink, C++**

Experience in **ROS1, FPGA** and **PLC** programming